How to Set Boot Parameters for the Different Linux Distributions
Planning / Implementation

There are lots of components during the Linux boot/installation process and each component has its own parameters. The following figure shows the high-level stages of a typical Linux boot process.
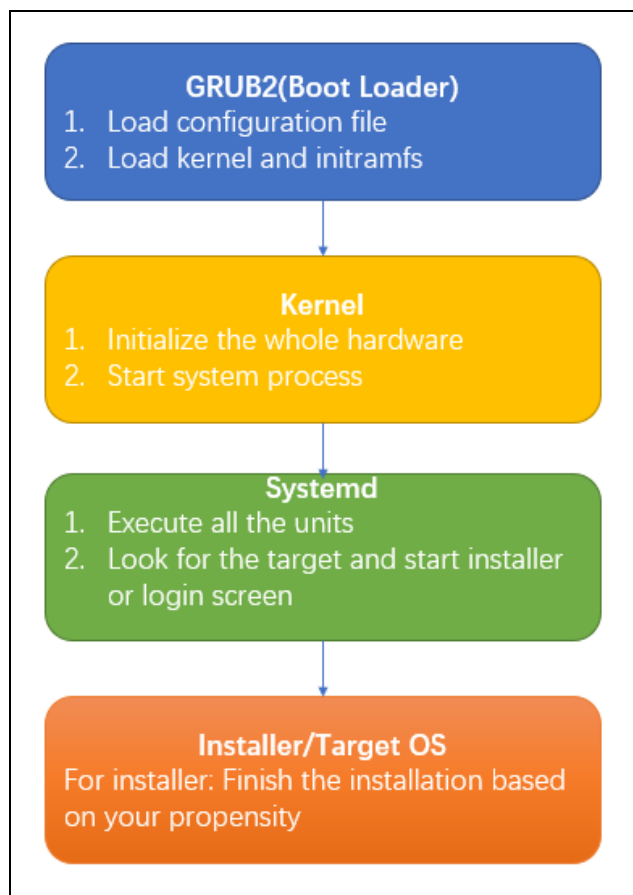

Figure 1. High-level stages of a typical Linux boot process

For the different Linux distributions, some parameters of above components are identical. However, different parameters among those distributions may have the same functionality. To avoid incorrect use of parameters, this chapter describes how to catch and set the relevant parameters about the different units.

The use of GRUB2

GRand Unified Bootloader version 2 (GRUB2) is a bootloader that allows user to quickly, easily and painlessly control the boot sequence of their systems. It is easy to get the usage with the following command.

```
Ubuntu OSes:        # info grub
RHEL and SUSE OSes: # info grub2
```

Alternatively, you can view the user manual on the GNU web site:
http:// https://www.gnu.org/software/grub/manual/grub/

The parameters of the installer

In this section, we introduce the parameters used in the different Linux installers.

- Anaconda
- Linuxrc
- Ubuntu installer

Anaconda

Anaconda is an installation program used by Red Hat Enterprise Linux, Fedora and some other distributions such as Asianux, Qubes OS, etc.

As different OS version contains different version of installer, download the relevant anaconda source package for the correct parameter. If you do not get the source package, refer to the close tag of https://github.com/rhinstaller/anaconda to find the parameter. Below is an example on RHEL 9.

1. Download the source package from https://access.redhat.com/.
2. Extract the file "boot-options.rst" from source package.

```
[root@rhel9 anaconda]# rpm2cpio anaconda-34.25.1.14-1.el9.src.rpm |cpio -div
anaconda-34.25.1.14.tar.bz2
anaconda.spec
7021 blocks
[root@rhel9 anaconda]# tar -jxf anaconda-34.25.1.14.tar.bz2
[root@rhel9 anaconda]#
[root@rhel9 anaconda]# find . -name boot-options.rst
./anaconda-34.25.1.14/docs/boot-options.rst
[root@rhel9 anaconda]#
```
Figure 2. Extract the file "boot-options.rst" from source package

3. Check the file boot-options.rst to find out the required parameter and the corresponding definition. The parameter "ip" is an example different from SUSE installer.

```
ip
^^

Configure one (or more) network interfaces. You can use multiple ``ip``
arguments to configure multiple interfaces, but if you do you must specify an
interface for every ``ip=`` argument, and you must specify which interface
is the primary boot interface with `bootdev`_.

Accepts a few different forms; the most common are:

.. ip=ibft:

``ip=<dhcp|dhcp6|auto6|ibft>``
    Try to bring up every interface using the given autoconf method.  Defaults
    to ``ip=dhcp`` if network is required by ``inst.repo``, ``inst.ks``, ``inst.updates``,
    etc.
```

Figure 3. ip parameter

Based on the guide of anaconda, the bootup is handled by dracut, so we can assume that the dracut options are also part of the anaconda parameters.

Those options can be shown with the command "man dracut.cmdline" or the following website:
https://mirrors.edge.kernel.org/pub/linux/utils/boot/dracut/dracut.html#dracutcmdline7

```
 root@rhel9 drac]# man Dracut.cmdline
DRACUT.CMDLINE(7)                                    dracut
DRACUT.CMDLINE(7)

NAME
    dracut.cmdline - dracut kernel command line options

DESCRIPTION
    The root device used by the kernel is specified in the boot configuration file on the kernel command
line, as always.

    The traditional root=/dev/sda1 style device specification is allowed, but not encouraged. The root
device should better be identified by LABEL or
    UUID. If a label is used, as in root=LABEL=<label_of_root> the initramfs will search all available
devices for a filesystem with the appropriate
    label, and mount that device as the root filesystem. root=UUID=<uuidnumber> will mount the
partition with that UUID as the root filesystem.
```

Figure 4. dracut man page

Linuxrc

Linuxrc is a small program that runs before the actual installation program YaST starts. The supporting parameter is included in the file linuxrc.html from the package "linuxrc". You can also refer to web page **en.opensuse.org/SDB:Linuxrc** directly, however it is better to choose the version close to the old OS in the "History" item. The following figure is the example different from RHEL ip parameter.

Figure 5. ifcfg parameter

Ubuntu installer

The default installer of Ubuntu 18.04 or earlier is Debian-installer(d-i). However, Ubuntu Server 20.04 or later introduces a new installer 'subiquity server installer' instead of the Debian-installer. As the d-i is about to be abandoned, this section mainly focuses on the 'subiquity'.

Subiquity contains three parts:

- Casper
- Curtin
- Cloud-init

The main boot options reside in Casper.

Refer to https://manpages.ubuntu.com/ for detailed information.

Kernel parameters

For kernel parameters, most of them are still consistent, such as nomodeset, iommu, acpi,etc. With the development of new features, new parameters have to be imported, such as no5lvl and hugetlb_free_vmemmap.

In order to check the supported boot parameter of your up-and-running OS, you can install kernel-doc package and get the available parameter list in the file kernel-parameters.txt (RHEL OS).

```
[root@localhost ~]# yum install -y -q kernel-doc

Installed:
  kernel-doc-5.14.0-162.6.1.el9_1.noarch

[root@localhost ~]#
[root@localhost ~]# find /usr/ -name "kernel-parameters.txt"
/usr/share/doc/kernel-doc-5.14.0-162.6.1.el9_1/Documentation/admin-guide/kernel-parameters.txt
[root@localhost ~]#
```

Figure 6. Installing kernel-doc

For SUSE OSes, please refer to https://github.com/openSUSE/kernel/blob/master/Documentation/admin-guide/kernel-parameters.txt, as the link is master branch by default, you need to switch to the relevant branch about OS version shown as follows.
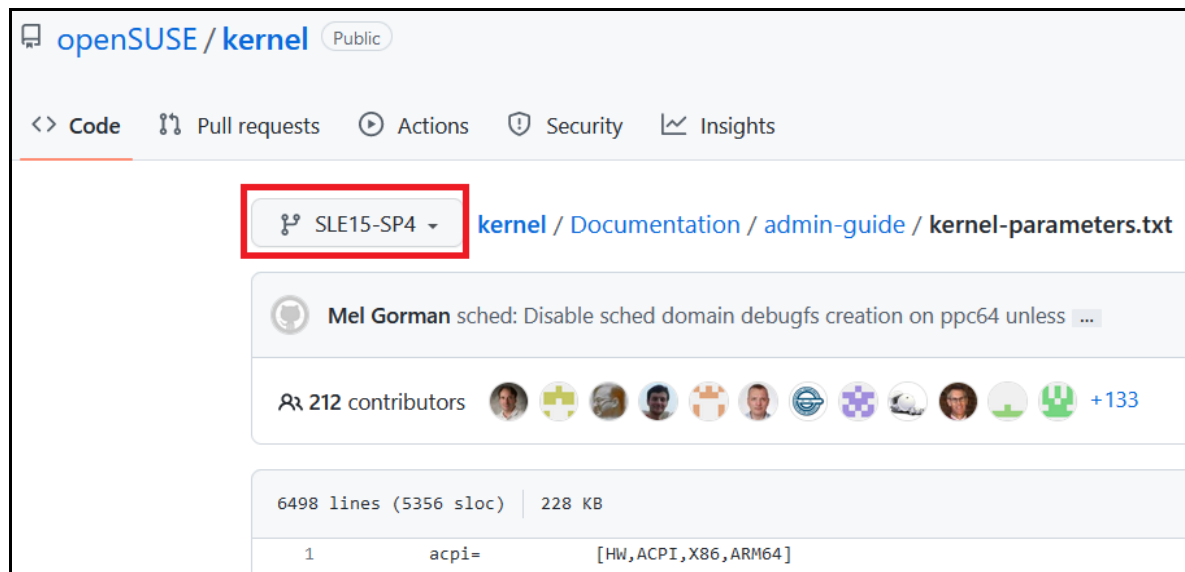
Figure 7. Kernel parameters information in openSUSE

For Ubuntu OSes, you can install linux-doc package and get the available parameter list in the file kernel-parameters.txt.gz.

Figure 8. Kernel parameters information in Ubuntu

Systemd parameters

Systemd is Linux's system and service manager. It is the parent process that starts as PID 1 and acts as an init system which starts and maintains user space services. There are some boot parameters for controlling system behavior.

Since it is opensource software, we can check the boot parameters in the https://github.com/systemd/systemd/blob/main/man/kernel-command-line.xml instead of decompressing the source package.

Applying the boot parameters

This section describes how to apply the parameters during installation and boot.

For the installer, the kernel and system apply parameters in the same way, but the server can be set up as a BIOS-based or UEFI-based system, thus you will get a different boot menu interface. Below is setup method on BIOS-based systems.

- RHEL
- SUSE
- Ubuntu 18.04 & 20.04
- UEFI-based systems

RHEL

Press the **Tab** key and add custom boot options to the command line, press "Enter" to continue booting, as shown in the following image.
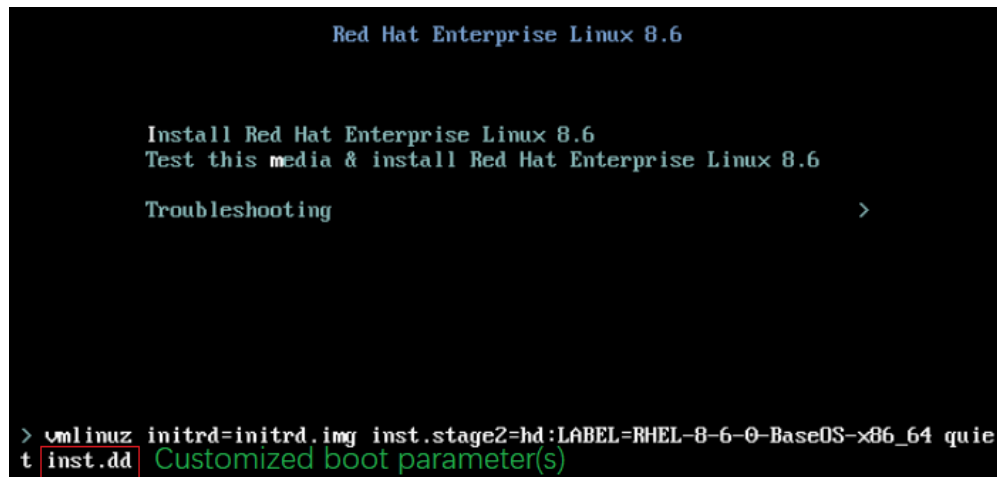

Figure 9. Prompt to press the tab key in RHEL

Figure 10. Entering custom boot options in RHEL

SUSE

Add custom boot options to the line "Boot Options" and press the **Enter** key to start the installation.
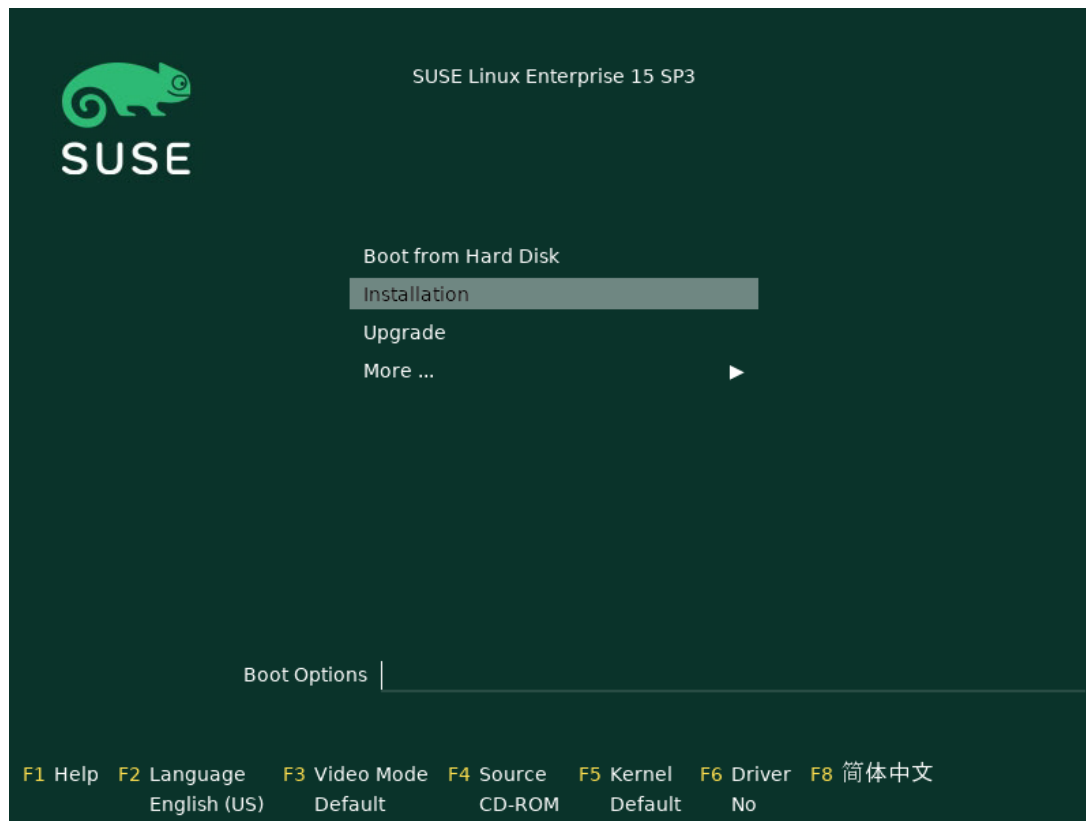
Figure 11. Custom boot options in SUSE

Ubuntu 18.04 & 20.04

For 22.04 refer to the next figure for UEFI-based systems below.

The line "Boot Options" is not displayed by default, it appears when the F6 key is pressed, adding custom boot options between "Boot Options" and text "---".
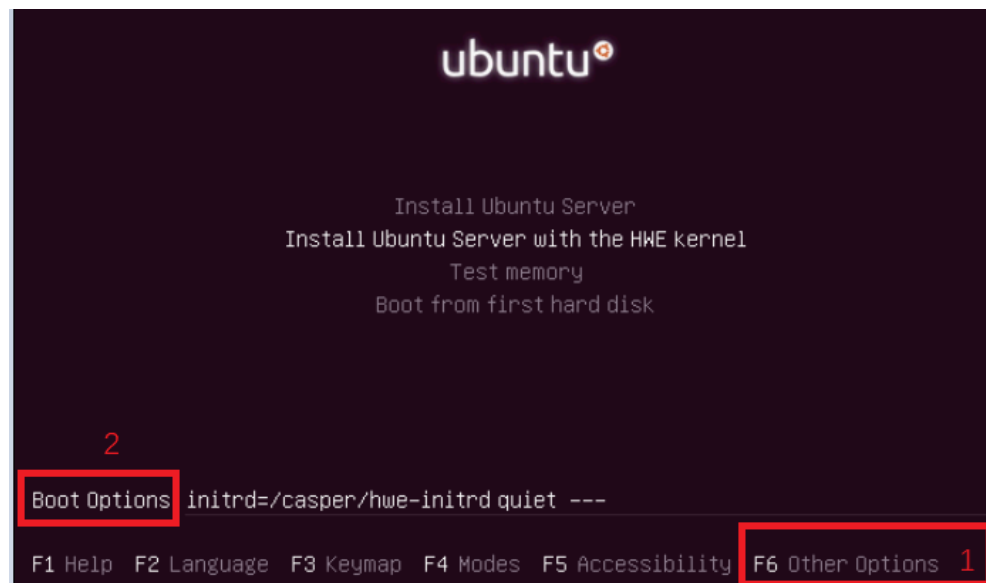
Figure 12. Custom boot options in Ubuntu

UEFI-based systems

Below is setup method on UEFI-based systems. It works in the same way for RHEL/SUSE/Ubuntu server (18.04,20.04,22.04[Both UEFI and BIOS]) OSes, with SLES 15.3 used below as an example.

Figure 13. SLES boot menu

Use the arrow keys to highlight the **Installation** entry and press "e" to add parameters to the end of the line that starts with `linuxefi` or `linux`, as shown below. To boot the edited entry, press F10 or other combination key based on the help at the bottom.

Figure 14. Adding parameters

Common parameters

This section introduces some common but ambiguous parameters and debug settings of GRUB2.
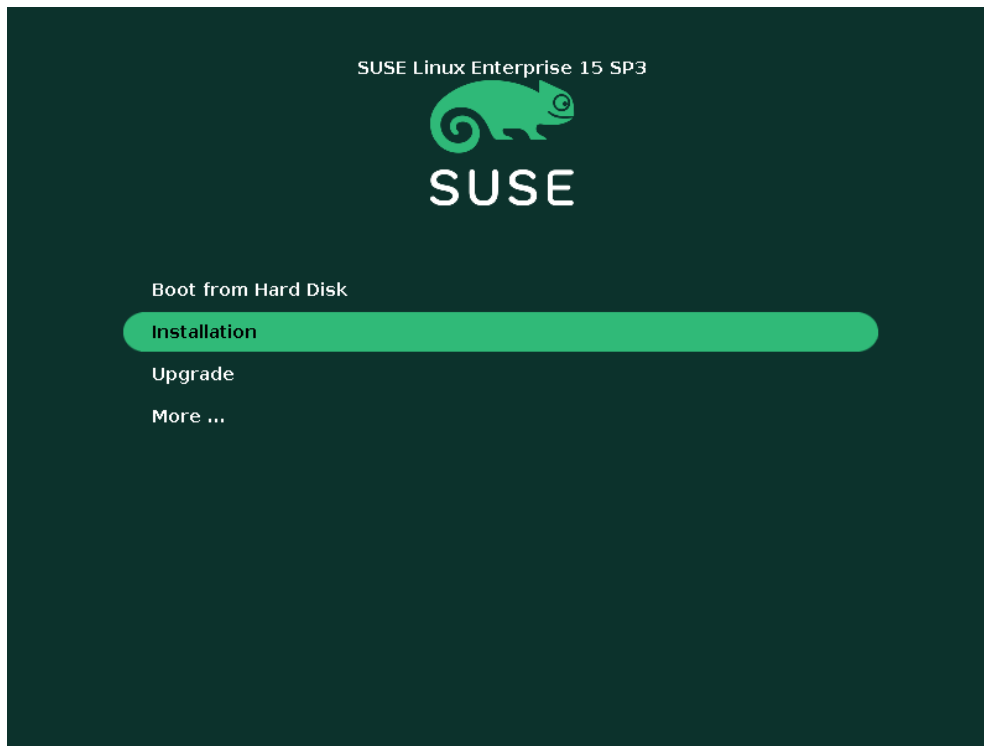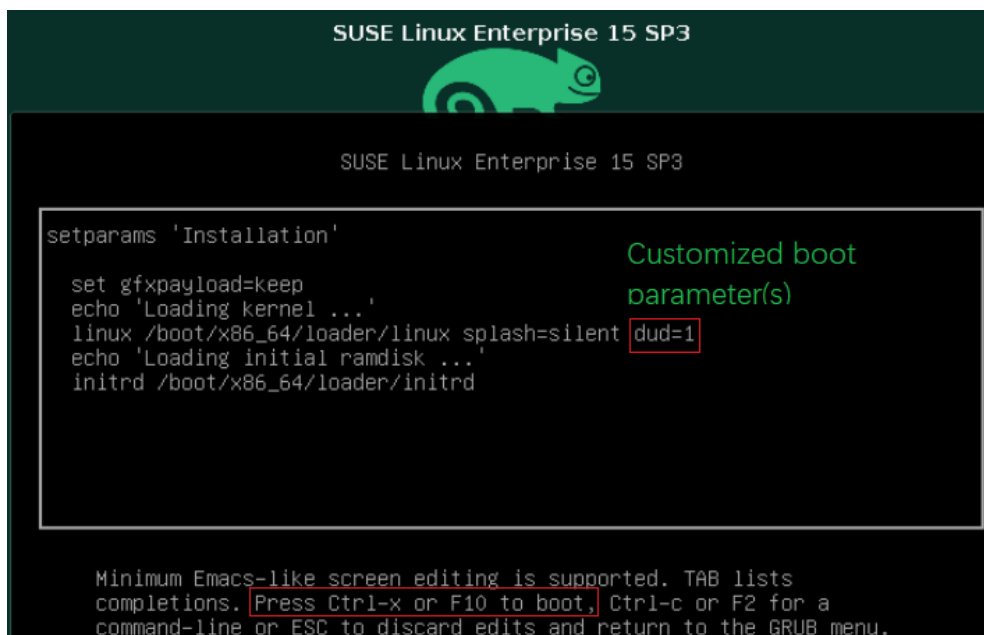
The following is the list of common parameters about different distributions.

Driver update parameters:

- **RHEL**:
  ```
  inst.dd=hd:LABEL=DISK_LABEL:/DRIVER.rpm
  inst.dd=http://IP/PATH/DRIVER.rpm
  ```
- **SLES**:
  ```
  dud=disk:/DRIVER.dud
  dud=http://IP/PATH/DRIVER.dud insecure=1
  ```
- **Ubuntu**:
  ```
  debian-installer/driver-update=
  ```

DHCP parameters:

- **RHEL**:
  ```
  ip=dhcp|auto6
  ```
- **SLES**:
  ```
  ifcfg=*=[dhcp|dhcp6]
  ```
- **Ubuntu**:
  ```
  ip=dhcp
  ```

Private parameters:

- **RHEL**:
  ```
  inst.addrepo=REPO_NAME,[http,https,ftp,nfs]:///
  ```
- **SLES**:
  1. `self_update=[0|1]`
  2. `addon=https://example.com/addon1,ftp://user:password@example.com/addon2`
- **Ubuntu**:
  ```
  toram
  todisk=DEVICE
  ```

Public parameters (all distributions):

1. Debug boot issue: `console=tty0 console=[ttyS0|ttyS1],[BAUD_RATE]n8` (where BAUD_RATE depends on UEFI setting)
2. Debug display issue: `nomodeset`

The following are the GRUB2 debug settings steps:

1. Enable the serial debug in the files "/etc/grub.d/00_header"and "/etc/default/grub".
   ```
   # cat /etc/grub.d/00_header  |grep -E "pager|debug"
   set pager=0
   set debug=all
   #
   ```
   Figure 15. Enable the serial debug in 00_header

   ```
   # cat /etc/default/grub |grep -Ew "GRUB_TERMINAL|GRUB_SERIAL_COMMAND"
   GRUB_TERMINAL="serial"
   GRUB_SERIAL_COMMAND="serial --speed=115200 --unit=0 --word=8 --parity=no --stop=1"
   #
   ```
   Figure 16. Enable the serial debug in grub

2. Rebuild the grub.cfg file using one of the following commands:

- RHEL 7 & RHEL 8 with UEFI:
  ```
  # grub2-mkconfig -o /boot/efi/EFI/redhat/grub.cfg
  ```

- RHEL 7 & RHEL 8 with Legacy BIOS
  ```
  # grub2-mkconfig -o /boot/grub2/grub.cfg
  ```

- RHEL 9:
  ```
  # grub2-mkconfig -o /boot/grub2/grub.cfg
  ```

- SLES:
  ```
  # grub2-mkconfig -o /boot/grub2/grub.cfg
  ```

- Ubuntu:
  ```
  # update-grub
  ```

Author

Song Shang is a Linux Engineer in Lenovo Infrastructure Solutions Group, based in TianJin, China.

Related product families

Product families related to this document are the following:

- Red Hat Enterprise Linux
- SUSE Linux Enterprise Server

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